

Minimal trap spaces of Boolean models are maximal siphons of their Petri net encoding

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Boolean modeling

Boolean modelling of **gene regulation** but also of other biological systems has had great successes over the last ~20 years.

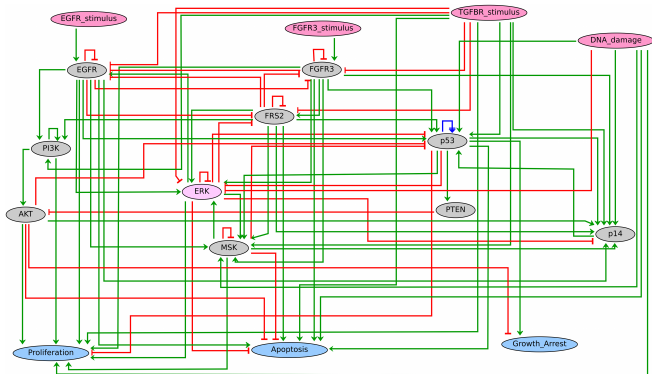


Figure: Boolean model of the MAPK regulatory network, whose involvement in bladder cancer is well established [Grieco et al., 2013].

Boolean models

Boolean model

A Boolean model \mathcal{M} is defined as a 2-tuple (V, F) , where $V = \{x_1, \dots, x_n\}$ ($n \geq 1$) is a set of nodes and $F = \{f_1, \dots, f_n\}$ is a set of Boolean functions. Each node x_i is identified as a Boolean variable, and is associated with a Boolean function $f_i : \mathbb{B}^{|IN(f_i)|} \rightarrow \mathbb{B}$, where $IN(f_i)$ is the set of input nodes of f_i .

A state s is a mapping $s : V \mapsto \mathbb{B}$ that assigns either 0 (inactive) or 1 (active) to each node.

The state space of \mathcal{M} is \mathbb{B}^n .

Dynamics of Boolean models

At each time step t , node x_i can update its state by

$$x_i(t + 1) = f_i(\mathbf{x}(t)).$$

An update scheme specifies which node will be updated.

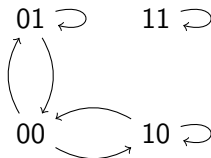
Based on the update scheme, the Boolean model can transit from a state to another state (possibly identical). This is the *state transition* (denoted by \longrightarrow).

The dynamics of a Boolean model is captured by a *State Transition Graph* (STG) that is a directed graph whose nodes represent states and whose arcs represent the state transitions.

Example Boolean model

$$\begin{cases} f_1 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \\ f_2 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \end{cases}$$

Boolean model



State transition graph

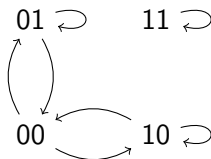
Fully asynchronous update scheme: only one node is nondeterministically selected in order to be updated at each time step.

Trap sets and attractors

A *trap set* is a non-empty set S of states s.t. $\forall x \rightarrow y, x \in S \Rightarrow y \in S$.

An *attractor* of a Boolean model is defined as a minimal trap set that does not contain any other trap set as a subset.

$$\begin{cases} f_1 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \\ f_2 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \end{cases}$$



State set	Trap set?	Attractor?
{11}	yes	yes
{00, 01}	no	no
{00, 01, 10}	yes	yes
{00, 01, 10, 11}	yes	no

Application

Besides simulation, the analysis of Boolean models is mostly based on *attractor* computation, since those correspond roughly to observable biological *phenotypes*.

Analysis of attractors could provide new insights into systems biology [Wang et al., 2012] (e.g., the origins of **cancers** [Montagud et al., 2021], **SARS-CoV-2** [Ostaszewski et al., 2021], **HIV** [Oyeyemi et al., 2014]).

Attractor computation also gives a **starting point** for many control approaches for biological systems [Fontanals et al., 2020], which play an important role in **the development of new drugs** [Balbas-Martinez et al., 2018].

Motivation

Attractor computation of Boolean models is very challenging [Mizera et al., 2019].

The recent use of *trap spaces* as very good approximations of attractors made a **real breakthrough** in that field allowing to consider medium-sized models that used to be out of reach [Klarner et al., 2015].

However, with the continuing increase in model-size, the state-of-the-art computation of minimal trap spaces based on *prime-implicants* (e.g., PyBoolNet [Klarner et al., 2017]) shows its **limits** as there can be a huge number of implicants.

The recent method presented in [Chevalier et al., 2019] for computing minimal trap spaces avoids the prime-implicants computation. It is implemented in the tool mpbn [Paulevé et al., 2020] and can handle very large but only *locally-monotonic* Boolean models.

Contribution

In this work [Trinh et al., 2022], we

- make a connection between trap spaces of Boolean models and siphons of Petri nets, which has not yet been explored before;
- and then propose a novel method to compute minimal trap spaces, and hence attractors, of a Boolean model.

Note that these results are applicable for **general** Boolean models (i.e., both locally-monotonic and non-locally-monotonic ones).

Subspaces

A *subspace* m is defined as a mapping $m : V \mapsto \mathbb{B} \cup \star$.

The set of fixed variables of m (denoted by D_m) is defined by $D_m := \{v \mid v \in V, m(v) \neq \star\}$.

The set of free variables of m is simply $V \setminus D_m$.

m is equivalent to a set of states

$$S[m] := \{s \in \mathbb{B}^n \mid \forall x_i \in D_m : s(x_i) = m(x_i)\}.$$

For example, $m = 01\star$ means that $D_m = \{x_1, x_2\}$, $m(x_1) = 0$, $m(x_2) = 1$, $m(x_3) = \star$, and m refers to the set of states $\{010, 011\}$.

Minimal trap spaces

A *trap space* is a set S of states that is a subspace and also a trap set.

A trap space is *minimal* if it does not contain any smaller trap space.

State set	Trap set?	Subspace?	Trap space?
$\{11\}$	yes	11	yes
$\{00, 01\}$	no	0*	no
$\{00, 01, 10\}$	yes	no	no
$\{00, 01, 10, 11\}$	yes	**	yes

Note that trap spaces of a Boolean model are **independent** of the update scheme of this model [Klarner et al., 2015].

Each minimal trap space contains at least one attractor, thus minimal trap spaces are good approximations for attractors of a Boolean model.

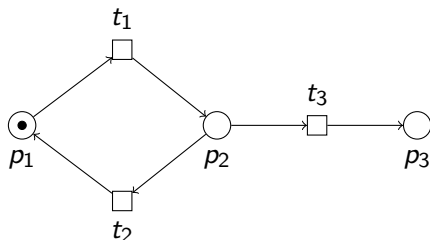
Petri nets

Bipartite graph

Places P

Transitions T

Weighted arcs W



A *marking* for a Petri net is a mapping $m : P \mapsto \mathbb{N}$ that assigns a number of tokens to each place. A place p is marked by a marking m if and only if $m(p) > 0$. For example, p_1 is marked, p_2 and p_3 are unmarked.

We shall write $pred(x)$ (resp. $succ(x)$) to represent the set of vertices that have a (non-zero weighted) arc leading to (resp. coming from) x . For example, $pred(p_2) = \{t_1, t_2\}$, $succ(p_2) = \{t_3\}$, $pred(t_2) = \{p_1\}$, and $succ(t_2) = \{p_2\}$.

Siphons

Siphon

A *siphon* of a Petri net (P, T, W) is a set of places S such that:

$$\forall t \in T, S \cap \text{succ}(t) \neq \emptyset \Rightarrow S \cap \text{pred}(t) \neq \emptyset.$$

Once a siphon is unmarked, it remains unmarked.

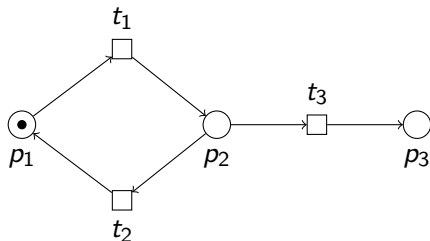
$S = \{p_1, p_3\}$ is not a siphon because

$$S \cap \text{succ}(t_3) = \{p_1, p_3\} \cap \{p_3\} =$$

$$\{p_3\} \neq \emptyset \text{ but}$$

$$S \cap \text{pred}(t_3) = \{p_1, p_3\} \cap \{p_2\} = \emptyset.$$

Here: $\emptyset, \{p_1, p_2\}, \{p_1, p_2, p_3\}$



Petri net of a Boolean model

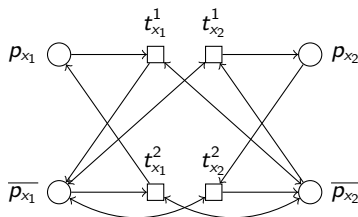
The original encoding was established in [Chaouiya et al., 2004].

Two places for each gene: $v \rightsquigarrow p_v, \bar{p}_v$

Solutions of $f_v \not\leftrightarrow v \rightsquigarrow$ transitions from p_v to \bar{p}_v (and back)

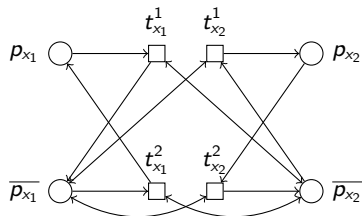
At any marking m of the Petri net encoding a Boolean model, it always holds that $m(p_v) + m(\bar{p}_v) = 1$.

$$\begin{cases} f_1 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \\ f_2 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \end{cases}$$



Conflict-free siphons

A siphon is called **conflict-free** if it does not contain both p_v and $\overline{p_v}$ for all $v \in V$.



Siphon	Conflict-free?
\emptyset	yes
$\{\overline{p_{x_1}}, \overline{p_{x_2}}\}$	yes
$\{p_{x_1}, \overline{p_{x_1}}\}$	no
$\{p_{x_2}, \overline{p_{x_2}}\}$	no

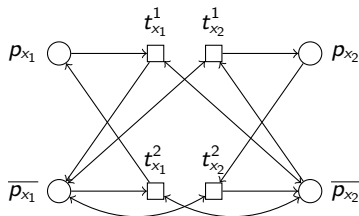
A conflict-free siphon is *maximal* if it is not a subset of any other conflict-free siphon.

Conflict-free siphons are trap spaces

Theorem 1

Let \mathcal{M} be a Boolean model and \mathcal{P} be its Petri net encoding. There is a **one-to-one correspondence** between the set of **trap spaces** of \mathcal{M} and the set of **conflict-free siphons** of \mathcal{P} .

$$\begin{cases} f_1 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \\ f_2 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \end{cases}$$



Trap space	Conflict-free siphon
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★ ★	\emptyset
-----	-------------

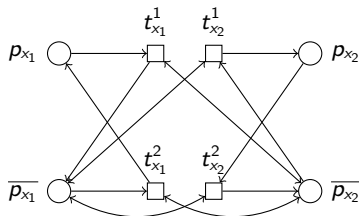
11	$\{\overline{p_{x_1}}, \overline{p_{x_2}}\}$
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Maximal conflict-free siphons are minimal trap spaces

Theorem 2

Let \mathcal{M} be a Boolean model and \mathcal{P} be its Petri net encoding. There is a **one-to-one correspondence** between the set of **minimal trap spaces** of \mathcal{M} and the set of **maximal conflict-free siphons** of \mathcal{P} .

$$\begin{cases} f_1 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \\ f_2 = (x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2) \end{cases}$$



Trap space	Conflict-free siphon
★★	\emptyset
11	$\{\overline{p_{x_1}}, \overline{p_{x_2}}\}$

Proposed method for minimal trap space computation

From Theorem 2, we propose a new method for computing minimal trap spaces of a Boolean model \mathcal{M} .

- Build the Petri net encoding \mathcal{P} of \mathcal{M} .
- Compute all maximal conflict-free siphons of \mathcal{P} .
- Convert the obtained maximal conflict-free siphons into the corresponding minimal trap spaces.

Petri net transformation

Transforming a Boolean model into its Petri net encoding can be done via computing Disjunctive Normal Forms (DNF) of each Boolean function [Chatain et al., 2014].

Though this might appear quite computationally intensive it is important to remark first that contrary to the prime-implicants case, there is no need to find *minimal* DNFs.

We use the above transformation in our proposed method. The implementation uses BDDs¹.

¹<https://github.com/cjdrake/pyeda>

Maximal conflict-free siphon computation

Characterize all siphons of the encoded Petri net as a system of Boolean rules.

$$p \in S \Rightarrow \bigvee_{p' \in \text{pred}(t)} p' \in S, p \in P, t \in T, t \in \text{pred}(p)$$

Add to the system the Boolean rules representing the conflict-freeness.

$$p_v \in S \Rightarrow \overline{p_v} \notin S \wedge \overline{p_v} \in S \Rightarrow p_v \notin S, v \in V$$

Encode the system as an ASP.

Use an ASP solver (e.g., clingo [Gebser et al., 2011]) to compute all set-inclusion maximal answer sets of the ASP.

Set-maximality through “heuristics”

```
clingo --heuristic=Domain --enum-mod=domRec --dom-mod=3
```

Locally-monotonic vs. non-locally-monotonic

A Boolean function is *locally-monotonic* if it can be represented by a formula in disjunctive normal form in which all occurrences of any given literal are either negated or non-negated [Anthony, 2001].

Function	locally-monotonic?	non-locally-monotonic?
$x \wedge y$	yes	no
$(x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2)$	no	yes

A Boolean model is said to be locally-monotonic if all its Boolean functions are locally-monotonic. Otherwise, this model is said to be non-locally-monotonic.

General models = locally-monotonic models + non-locally-monotonic models

Locally-monotonic vs. non-locally-monotonic (cont.)

Method	Applicable domain
mpbn [Paulevé et al., 2020]	locally-monotonic
PyBoolNet [Klarner et al., 2017]	general
our proposed method	general

mpbn is specifically designed for exploiting the locally-monotonicity [Paulevé et al., 2020]. Hence, for locally-monotonic Boolean models, it has many advantages over other methods.

It is worth noting that the study [Noual et al., 2013] highlights the need for non-locally-monotonic Boolean models in both biological and theoretical aspects.

PyBoolNet repo, 1000 first solutions our proposed method

model	n	$ M $	PyBoolNet	mpbn	Trappist
arellano_rootstem	9	4	0.05	0.01	0.02
calzone_cellfate	28	27	0.03	0.02	0.03
dahlhaus_neuroplastoma	23	32	0.06	0.02	0.03
		...			
jaoude_thdiff	103	>1000	1.92	1.32	0.20
klamt_tcr	40	8	0.04	0.01	0.04
		...			
n5s3	4	3	0.03	NM	0.02
		...			
randomnet_n15k3	15	3	0.04	NM	0.04
randomnet_n7k3	7	10	0.03	NM	0.02
remy_tumorigenesis	34	25	2.05	0.04	0.06
saadatpour_guardcell	13	1	0.02	0.00	0.02
selvaggio_emt	56	>1000	1.09	0.76	0.18
tourner_apoptosis	12	3	0.03	0.01	0.02
xiao_wnt5a	7	4	0.03	0.00	0.02
zhang_tlg1	60	156	0.22	0.22	0.09
zhang_tlg1_v2	60	258	0.11	0.24	0.08

PyBoolNet repo, 1000 first solutions

model	n	$ M $	PyBoolNet	mpbn	Trappist
arellano_rootstem	9	4	0.05	0.01	0.02
calzone_cellfate	number of nodes	7	0.03	0.02	0.03
dahlhaus_neuroplastoma	23	number of minimal trap spaces			0.03
		...			
jaoude_thdiff	103	>1000	1.92	1.32	0.20
klamt_tcr	40	8	0.04	0.01	0.04
		...			
n5s3	non-monotonic model		0.03	NM	0.02
		...			
randomnet_n15k3	15	3	0.04	NM	0.04
randomnet_r	significant difference to		0.03	NM	0.02
remy_tumori	the best running time (in		2.05	0.04	0.06
saadatpour_l	seconds)		0.02	0.00	0.02
selvaggio_emt	56	>1000	1.09	0.76	0.18
tourner_apoptosis	12	3	0.03	0.01	0.02
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		...			
jaoude_thdiff	103	>1000	1.92	1.32	0.20
klamt_tcr	40	8	0.04	0.01	0.04
		...			
<p>All three methods are comparable with all minimal trap spaces found very fast because the models are quite small.</p>					
randomnet_n15k3	15	3	0.04	NM	0.04
randomnet_n7k3	7	10	0.03	NM	0.02
remy_tumorigenesis	34	25	2.05	0.04	0.06
saadatpour_guardcell	13	1	0.02	0.00	0.02
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jacoudo_tbdiff	102	>1000	1.00	1.22	0.20
k					4
n5s3	4	3	0.03	NM	0.02
randomnet_n15k3	15	3	0.04	NM	0.04
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zhang_tlg1	60	156	0.22	0.22	0.09
zhang_tlg1_v2	60	258	0.11	0.24	0.08

For 3 of the 29 models, mpbn did not give any answer because these models are non-locally-monotonic.

PyBoolNet repo, 1000 first solutions

model	n	$ M $	PyBoolNet	mpbn	Trappist
arellano_rootstem	9	4	0.05	0.01	0.02
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On every model that was a bit challenging for PyBoolNet or mpbn, the new method is more efficient with significant speedups.

n

2

Large models from literature, 2 min timeout

model	n	$ M $	PyBoolNet	mpbn	Trappist
inflammatory-bowel	47	1	DNF	NM	1.71
T-LGL-survival	61	318	0.23	0.30	0.10
butanol-production	66	>1000	0.20	0.88	0.12
colon-cancer	70	10	0.07	0.04	0.06
mast-cell-activation	73	>1000	0.16	0.89	0.13
IL-6-signalling	86	>1000	0.17	1.01	0.13
Corral-Th1L-17-diff	92	>1000	DNF	1.18	0.18
Korkut-2015	99	>1000	DNF	1.36	0.39
adhesion-cip-migration	121	78	28.77	0.34	0.25
interferon-1	121	>1000	2.82	1.42	0.17
TCR-TLR5-signaling	130	48	0.54	0.18	0.13
influenza-replication	131	>1000	8.75	1.54	0.20
prostate-cancer	133	>1000	DNF	2.71	0.38
HIV-1	138	>1000	DNF	11.77	0.36
fibroblasts	139	>1000	DNF	NM	0.42
HMOX-1-pathway	145	>1000	1.65	1.98	0.20

Large models from literature, 2 min timeout (cont.)

model	n	$ M $	PyBoolNet	mpbn	Trappist
		...			
MAPK	181	>1000	86.81	2.64	0.30
er-stress	182	>1000	11.13	2.26	0.24
cascade-3	183	1	DNF	0.33	0.24
CHO-2016	200	>1000	DNF	3.36	0.36
T-cell-check-point	218	>1000	28.83	NM	0.38
ErbB-receptor-signaling	247	>1000	DNF	NM	1.06
macrophage-activation	321	>1000	10.47	3.86	0.50
cholocystokinin	383	>1000	2.83	4.46	0.49
Alzheimer	762	>1000	DNF	NM	0.99
KEGG-network	1659	>1000	DNF	21.57	30.22
human-network	1953	>1000	DNF	25.19	21.91
SN-5	2746	>1000	DNF	37.54	45.57
turei-2016	4691	>1000	DNF	119.98	DNF

Large models from literature, 2 min timeout (cont.)

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T-cell-check-point	218	>1000	28.83	NM	0.38
<p style="color: red;">These models are quite big (in size), complex (i.e., having high average in-degree) and most of them have never been fully analyzed.</p>					
cholocystokinin	383	>1000	2.83	4.46	0.49
Alzheimer	762	>1000	DNF	NM	0.99
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For 6 of the 33 models, mpbn did not give any answer because these models are non-locally-monotonic.					
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CHO-2016	200	>1000	DNF	3.36	0.36
T-cell-check-point	218	>1000	28.83	NM	0.38
For 26 of the 33 models where both mpbn and Trappist returned the answers, they are comparable in computation time, though surprisingly mpbn appears a bit slower on average.					
Alzheimer	762	>1000	DNF	NM	0.99
KEGG-network	1659	>1000	DNF	21.57	30.22
human-network	1953	>1000	DNF	25.19	21.91
SN-5	2746	>1000	DNF	37.54	45.57
turei-2016	4691	>1000	DNF	119.98	DNF

Large models from literature, 2 min timeout (cont.)

model	n	$ M $	PyBoolNet	mpbn	Trappist
		...			
MAPK	181	>1000	86.81	2.64	0.30
er-stress	182	>1000	11.13	2.26	0.24
cascade-3	183	1	DNF	0.33	0.24
CHO-2016	200	>1000	DNF	3.36	0.36
T-cell-check-point	218	>1000	28.83	NM	0.38
<p>Note however that mpbn was the only tool to provide a solution for the turei model within two minutes, thus confirming its advantages for locally-monotonic models.</p>					
Alzheimer	762	>1000	DNF	NM	0.99
KEGG-network	1659	>1000	DNF	21.57	30.22
human-network	1953	>1000	DNF	25.19	21.91
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The proposed method vastly outperforms PyBoolNet in computational time, on each and every model, and sometimes with orders of magnitude of difference.					
Alzheimer	762	>1000	DNF	NM	0.99
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Conclusion

Minimal trap spaces are important in Boolean model analysis.

We linked the concept of trap spaces in the Boolean networks field and the concept of siphons on the Petri nets field.

We proposed a new method for the computation of minimal trap spaces of Boolean models.

The evaluation on large models from the literature shows that

- our method can scale up much better than the state-of-the-art **prime-implicants** based techniques for non-locally-monotonic models;
- our method is comparable to mpbn for locally-monotonic models.

We believe that this opens up the way to a much better analysis of large Boolean models, hence **biological systems**.

Future work




Improve our method to deal with **larger and more complex** models.

Extend our method to that for **multi-level logical models**, which can model biological systems better.

Finally, we think that the links between Petri nets and Boolean models that we stumbled upon in this method might have deeper roots. Exploring those connections might lead both to interesting topics of research for Petri nets, like a notion of trap spaces, and for Boolean models.

Thank you for your attention!

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